







Aerodynamics Assessment and Development of Smokey SAM Rocket Prototype

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Research motivation

□ Introduction

Research methodology

Results & discussions

Research Significance

Smokey SAM Rocket

Significance

- small unguided rocket developed
- as a threat simulator for use during military exercises







- Save cost during military training
- Reduce risk
- Test the pilot sensitivity of detecting threat from the ground

Introduction

GTR-18 Smokey SAM

 The GTR-18 was invented in the late 1970s by Robert A. McLellan, a Weapons Range Scientist working with Exercise Red Flag at Nellis Air Force Base. He first sought a commercially available system that would function as he envisioned.

 It quickly became visible that no commercial product would perform satisfactorily, so the development of the GTR-18 was undertaken by the Naval Weapons Center (NWC) during the early 1980s to develop Mr McLellan's idea of a simple and inexpensive rocket for visually simulating the launch of surface-to-air missiles (SAMs) during training exercises.



Design Requirements & Objectives (DRO)



Modelling Scheme Flowchart



End

Geometric parameters of the design through OpenRocket modelling

Parameter	Components				
	Nose cone	Body tube	Fins	Launch Lug 1	Launch Lug 2
Shape	Ellipsoid	n/a	Trapezoidal	n/a	n/a
Length (cm)	10.00	28.00	n/a	3.00	3.00
Base diameter (cm)	5.00	n/a	n/a	n/a	n/a
Thickness (cm)	0.20	0.30	0.20	0.10	0.10
Shoulder diameter (cm)	4.60	n/a	n/a	n/a	n/a
Shoulder length (cm)	3.00	n/a	n/a	n/a	n/a
Outer diameter (cm)	n/a	5.00	n/a	1.00	1.00
Inner diameter (cm)	n/a	4.40	n/a	0.80	0.80
Cross section	n/a	n/a	Square	n/a	n/a
Number of fins	n/a	n/a	5.00	n/a	n/a
Root chord (cm)	n/a	n/a	7.00	n/a	n/a
Tip chord (cm)	n/a	n/a	3.00	n/a	n/a
Height (cm)	n/a	n/a	7.00	n/a	n/a
Sweep length (cm)	n/a	n/a	4.04	n/a	n/a
Sweep angle (°)	n/a	n/a	30.00	n/a	n/a
Radial position (°)	n/a	n/a	n/a	40.00	40.00
Position relative to top of parent component (cm)	n/a	n/a	n/a	10.50	10.50

Design - Modelling



Developed Smokey SAM model for CFD analysis

CFD - Modelling



Meshing element on presented Smokey SAM model

Present model element meshing parameters

Fin: Length = 0	.07 m, Area = 0.0	03403	m²			
Kinematic	Density,	ρ	Velocity,	V	y+, (m)	Re
viscosity, μ	(kg/m³)	(m/s)			
$1.508 x 10^{-5}$	1.178		54.60		5.059×10^{-6}	$2.986x10^5$
			40.00		6.754×10^{-6}	$2.188x10^5$
			25.00		$1.045 x 10^{-6}$	1.367×10^5
Body: Length = 0.37 m, Area = 0.005346 m ²						
Kinematic	Density,	ρ	Velocity,	V	y+, (m)	Re
viscosity, μ	(kg/m³)	(m/s)			
$1.508 x 10^{-5}$	1.178		54.60		5.698×10^{-6}	$1.578x10^{6}$
			40.00		$7.607 x 10^{-6}$	$1.156x10^{6}$
			25.00		1.17710^{-6}	7.227×10^5

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Design – Rocket Motor Testing

Quest C6



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Design - Modelling

Tested Rocket Motor for Designed Smokey SAM (Open-source software: OpenRocket)

Parameter			Single-use motor			
-	AeroTech E15	AeroTech D21	Apogee C10	Quest C6	Estes E16	
Manufacturer	AeroTech	AeroTech	Apogee	Quest	Estes	
Designation	E15W-4	D21-7	C10-4	C6-5	E16-4	
Total Impulse (Ns)	40	20.00	10.00	9.00	34.00	
Diameter (cm)	2.40	1.80	1.80	1.80	2.90	
Length (cm)	7.00	7.00	5.00	7.00	11.40	

Results & discussions

Velocity & Flow Distributions



Velocity contour at fin for (a) V = 54.6 m/s, (b) V = 40m/s, and (c) V = 25m/s



Fin						
V, m/s	Lift, N	Lift Coefficient <i>, C_l</i>	Drag, N	Drag Coefficient, <i>C_d</i>	Moment, N.m	Moment Coefficient
54.60	0.049	0.00822	0.274	0.0232	0.023	0.056
40.00	0.026	0.00810	0.153	0.0227	0.013	0.057
25.00	0.010	0.00788	0.062	0.0223	0.005	0.057

Results & discussions

Velocity & Flow Distributions

Velocity contour of whole rocket body for (a) V = 54.6m/s, (b) V = 40m/s, and (c) V = 25m/s



Results & discussions

Launching Set-Up





Future works

Telemetry System





Future works (avionics system integration)

Guidance System



Conclusion

- This paper intends to study the rocket's aerodynamics performance when flying; the aerodynamics analysis on the Smokey SAM prototype rocket has not been widely studied yet. The aerodynamics loads acting on the rocket body must ensure the steady flight condition can be achieved.
- Observation can be made from the real time flight test validation. The flight test was successful since the rocket managed to stabilise itself despite the instability while leaving the rod. Thus, this validate the CFD simulation where the aerodynamics loads acting on the rocket is low thus that ensure the rocket to have a good and stable flight path.
- In terms of body contribution, the trend is just the same as fin where the simulation recorded that as the speed increases, the pressure also increases.

Acknowledgment



The authors would like to express their gratitude and thanks to Lestari Aero Industries Sdn Bhd, Title: Design & Development of Smokey SAM Prototype (TRL-6) – STAR (X).