



Document details

< Back to results | 1 of 1

↗ Export Download Print E-mail PDF Save to PDF ☆ Add to List More... >

Full Text

View at Publisher

International Journal of Control
2020

Improving the use of feedforward in Predictive Functional Control to improve the impact of tuning

Article in press ?

Rossiter, J.A.^a E-mail Abdullah, M.^b

^aDepartment of Automatic Control and Systems Engineering, The University of Sheffield, Sheffield, United Kingdom

^bDepartment of Mechanical Engineering, International Islamic University Malaysia, Kuala Lumpur, Malaysia

Abstract

View references (17)

The classic PFC design is simple and intuitive and yet this paper shows that, counter to expectations, the long standing use of the target information is flawed. Some simple illustrations will demonstrate that what appears sensible can in fact lead to inconsistent decision-making with many common process dynamics. Having explored the source of this inconsistency, the paper shows how it can be ameliorated in a systematic fashion and also investigates the impact of the change on loop sensitivity to disturbances. Several numerical examples demonstrate the efficacy of the proposal in the paper. © 2020 Informa UK Limited, trading as Taylor & Francis Group.

SciVal Topic Prominence ⓘ

Topic: Generalized Predictive Control | Constraint Handling | Pole Placement

Prominence percentile: 65.312



Author keywords

feed-forward control

Predictive functional control

preview control

Indexed keywords

Engineering controlled terms:

Computer applications

Control engineering

Engineering uncontrolled terms

Common process

Feed-Forward

Predictive functional control

Target information

Engineering main heading:

Decision making

Metrics ⓘ View all metrics >



PlumX Metrics

Usage, Captures, Mentions, Social Media and Citations beyond Scopus.

Cited by 0 documents

Inform me when this document is cited in Scopus:

Set citation alert >

Related documents

A new paradigm for predictive functional control to enable more consistent tuning

Rossiter, J.A. , Abdullah, M. (2019) *Proceedings of the American Control Conference*

Input shaping predictive functional control for different types of challenging dynamics processes

Abdullah, M. , Rossiter, J.A. (2018) *Processes*

Using Laguerre functions to improve the tuning and performance of predictive functional control

Abdullah, M. , Rossiter, J.A. (2019) *International Journal of Control*




View all related documents based on references

Find more related documents in Scopus based on:

Authors > Keywords >

References (17)

[View in search results format >](#)

All [Export](#)  Print  E-mail  Save to PDF [Create bibliography](#)

-
- 1 Abdullah, M., Rossiter, J.A., Haber, R.
Development of Constrained Predictive Functional Control using Laguerre Function Based Prediction ([Open Access](#))

(2017) *IFAC-PapersOnLine*, 50 (1), pp. 10705-10710. Cited 11 times.
<http://www.journals.elsevier.com/ifac-papersonline/>
doi: 10.1016/j.ifacol.2017.08.2222

[View at Publisher](#)
-
- 2 Abdullah, M., Rossiter, J.A.
Input shaping predictive functional control for different types of challenging dynamics processes ([Open Access](#))

(2018) *Processes*, 6 (8), art. no. 118. Cited 3 times.
https://res.mdpi.com/processes/processes-06-00118/article_deploy/processes-06-00118.pdf?filename=&attachment=1
doi: 10.3390/pr6080118

[View at Publisher](#)
-
- 3 Clarke, D.W., Mohtadi, C., Tuffs, P.S.
Generalized predictive control-Part I. The basic algorithm

(1987) *Automatica*, 23 (2), pp. 137-148. Cited 2951 times.
doi: 10.1016/0005-1098(87)90087-2

[View at Publisher](#)
-
- 4 Khadir, M.T., Ringwood, J.V.
Extension of first order predictive functional controllers to handle higher order internal models ([Open Access](#))

(2008) *International Journal of Applied Mathematics and Computer Science*, 18 (2), pp. 229-239. Cited 25 times.
doi: 10.2478/v10006-008-0021-z

[View at Publisher](#)
-
- 5 Mayne, D.Q., Rawlings, J.B., Rao, C.V., Sokaert, P.O.M.
Constrained model predictive control: Stability and optimality

(2000) *Automatica*, 36 (6), pp. 789-814. Cited 5639 times.
doi: 10.1016/S0005-1098(99)00214-9

[View at Publisher](#)
-
- 6 Richalet, J., Donovan, D.
(2009) *Predictive functional control: principles and industrial applications*. Cited 129 times.
Springer-Verlag
-

- 7 Richalet, J., Rault, A., Testud, J.L., Papon, J.
Model predictive heuristic control. Applications to industrial processes
(1978) *Automatica*, 14 (5), pp. 413-428. Cited 1279 times.
doi: 10.1016/0005-1098(78)90001-8
[View at Publisher](#)
-
- 8 Rossiter, J.A.
Notes on multi-step ahead prediction based on the principle of concatenation
(1993) *Proceedings of the Institution of Mechanical Engineers. Part I, Journal of systems and control engineering*, 207 (4), pp. 261-263. Cited 15 times.
doi: 10.1243/PIME_PROC_1993_207_348_02
[View at Publisher](#)
-
- 9 Rossiter, J.A.
Input shaping for PFC: how and why? ([Open Access](#))
(2016) *Journal of Control and Decision*, 3 (2), pp. 105-118. Cited 11 times.
www.tandfonline.com/tjcd
doi: 10.1080/23307706.2015.1083408
[View at Publisher](#)
-
- 10 Rossiter, J.A.
A priori stability results for PFC ([Open Access](#))
(2017) *International Journal of Control*, 90 (2), pp. 305-313. Cited 9 times.
www.tandf.co.uk/journals/titles/00207179.asp
doi: 10.1080/00207179.2016.1178806
[View at Publisher](#)
-
- 11 Rossiter, J.A.
(2018) *A first course in predictive control*. Cited 16 times.
2nd ed., Taylor and Francis
-
- 12 Rossiter, J.A., Abdullah, M.
A new paradigm for predictive functional control to enable more consistent tuning
([Open Access](#))
(2019) *Proceedings of the American Control Conference*, 2019-July, art. no. 8814453, pp. 366-371.
ISBN: 978-153867926-5
doi: 10.23919/acc.2019.8814453
[View at Publisher](#)
-
- 13 Rossiter, J.A., Haber, R.
The effect of coincidence horizon on predictive functional control ([Open Access](#))
(2015) *Processes*, 3 (1), pp. 25-45. Cited 25 times.
<http://www.mdpi.com/2227-9717/3/1/25/pdf>
doi: 10.3390/pr3010025
[View at Publisher](#)
-

- 14 Rossiter, J.A., Haber, R., Zabet, K.
Pole-placement Predictive Functional Control for over-damped systems with real poles (Open Access)

(2016) *ISA Transactions*, 61, pp. 229-239. Cited 19 times.
http://www.elsevier.com/wps/find/journaldescription.cws_home/524244/description#description
doi: 10.1016/j.isatra.2015.12.003

[View at Publisher](#)

- 15 Saleheen Aftab, M., Rossiter, J.A.
(2020)
Predictive functional control with explicit pre-conditioning for oscillatory dynamic systems,. Submitted to UKACC Control Conference 2020 (under review), 6 pages

- 16 Zabet, K., Rossiter, J.A., Haber, R., Abdullah, M.
Pole-placement Predictive Functional Control for under-damped systems with real numbers algebra (Open Access)

(2017) *ISA Transactions*, Part 2 71, pp. 403-414. Cited 9 times.
http://www.elsevier.com/wps/find/journaldescription.cws_home/524244/description#description
doi: 10.1016/j.isatra.2017.08.002

[View at Publisher](#)

- 17 Zhang, Z., Rossiter, J.A., Xie, L., Su, H.
Predictive functional control for integrator systems

(2020) *Journal of the Franklin Institute*, 357 (7), pp. 4171-4186.
<https://www.journals.elsevier.com/journal-of-the-franklin-institute>
doi: 10.1016/j.jfranklin.2020.01.026

[View at Publisher](#)

🔍 Rossiter, J.A.; Department of Automatic Control and Systems Engineering, The University of Sheffield, Sheffield, United Kingdom; email:j.a.rossiter@sheffield.ac.uk
© Copyright 2020 Elsevier B.V., All rights reserved.

[Back to results](#) | 1 of 1

[Top of page](#)

About Scopus

What is Scopus
Content coverage
Scopus blog
Scopus API
Privacy matters

Language

日本語に切り替える
切换到简体中文
切换到繁體中文
Русский язык

Customer Service

Help
Contact us

ELSEVIER

[Terms and conditions](#) ↗ [Privacy policy](#) ↗

Copyright © Elsevier B.V. ↗. All rights reserved. Scopus® is a registered trademark of Elsevier B.V.

We use cookies to help provide and enhance our service and tailor content. By continuing, you agree to the use of cookies.

RELX