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# In-socket sensory system with an adaptive neuro-based fuzzy inference system for active transfemoral prosthetic legs

By: **Yusof, NHM** (Yusof, Nur Hidayah Mohd)<sup>[1]</sup>; **Hamzaid, NA** (Hamzaid, Nur Azah)<sup>[1]</sup>; **Jasni, F** (Jasni, Farahiyah)<sup>[1,2]</sup>; **Lai, KW** (Lai, Khin Wee)<sup>[1]</sup>  
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**Abstract**  
An in-socket sensory system enables the monitoring of transfemoral amputee movement for a microprocessor-controlled prosthetic leg. User movement recognition from an in-socket sensor allows a powered prosthetic leg to actively mimic healthy ambulation, thereby reducing an amputee's metabolic energy consumption. This study established an adaptive neurofuzzy inference system (ANFIS)-based control input framework from an in-socket sensor signal for gait phase classification to derive user intention as read by in-socket sensor arrays. Particular gait phase recognition was mapped with the cadence and torque control output of a knee joint actuator. The control input framework was validated with 30 experimental gait samples of the in-socket sensory signal of a transfemoral amputee walking at fluctuating speeds of 0 to 2 km.h(-1). The physical simulation of the controller presented a realistic simulation of the actuated knee joint in terms of a knee mechanism with 95% to 99% accuracy of knee cadence and 80% to 90% accuracy of torque compared with those of normal gait. The ANFIS system successfully detected the seven gait phases based on the amputee's in-socket sensor signals and assigned accurate knee joint torque and cadence values as output. (C) 2018 SPIE and IS&T

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**Author Information**  
**Reprint Address:** Lai, KW (reprint author)  
+ Univ Malaya, Dept Biomed Engn, Fac Engn, Kuala Lumpur, Malaysia.  
**Addresses:**  
+ [ 1 ] Univ Malaya, Dept Biomed Engn, Fac Engn, Kuala Lumpur, Malaysia  
+ [ 2 ] Int Islamic Univ Malaysia, Dept Mechatron Engn, Fac Engn, Kuala Lumpur, Malaysia  
**E-mail Addresses:** [khinwee@um.edu.my](mailto:khinwee@um.edu.my)

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