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Adaptive hybrid impedance control for a 3DOF upper limb rehabilitation robot using hybrid automata (Conference Paper)

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Abstract

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There is a growing need for effective and adaptive robot-assisted rehabilitation platforms for post-stroke patients which can facilitate considerably their sensorimotor control performance, and also ensure safety for the patients. © 2014 IEEE.

Indexed keywords

Engineering controlled terms: Biomedical engineering, Robots

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Hybrid impedance control
Post stroke patients
Robot-assisted rehabilitation
Sensorimotor control
Upper-limb rehabilitation

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