

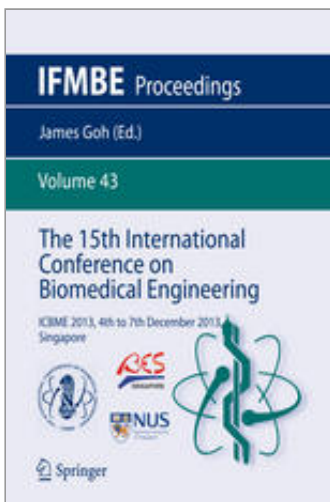
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The 15th International Conference on Biomedical Engineering
IFMBE Proceedings Volume 43, 2014, pp 767-770

Evolutionary Low Frequency Steering Vibration Control towards Human Spine

Abstract

This paper demonstrated a simulation study of an active vibration control using particle-swarm optimisation based proportional, integral and derivative (PSO-PID) control scheme to suppress steering vibration towards human vertebrae impact. The vertebrae dynamic model is identified based on grey-box modelling technique. This technique combines physical behaviour information of the spine via mathematical model and robust black-box model of the spine with added vehicle speed variation. The performance of PID-PSO control scheme is validated and compared with the conventional PID control scheme. PSO falls under the umbrella of evolutionary algorithms which is used to optimise and tune the PID controller parameters (K_p , K_i and K_d) based on a predefined performance index. The main objective is to minimise the mean square error (MSE) of the vibration signal. The optimum PSO-PID parameters are then used to suppress vibration induced by steering vehicles to the spine. This study showed that PSO-PID is better tuned than the conventional tuning method in terms of transient response.



About this Chapter

Title

Evolutionary Low Frequency Steering Vibration Control towards Human Spine

Book Title

The 15th International Conference on Biomedical Engineering

Book Subtitle

ICBME 2013, 4th to 7th December 2013, Singapore

Pages

pp 767-770

Copyright

2014

DOI

10.1007/978-3-319-02913-9_197

Print ISBN

978-3-319-02912-2

Online ISBN

978-3-319-02913-9

Series Title

IFMBE Proceedings

Series Volume

43

Series ISSN

1680-0737

Publisher

Springer International Publishing

Copyright Holder

Springer International Publishing Switzerland

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