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A CASE STUDY ON DESIGN AND MANUFACTURE OF TILTING PAD THRUST BEARING FOR STEAM TURBINE OF FERTILIZER FACTORIES

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Abstract:

Bangladesh has to depend mainly on imported spare parts for maintenance of its major industries. The picture is not different in the case of the fertilizer factories. Tilting pad thrust bearing is a critical and very expensive spare part of fertilizer factories. Like many other spares this spare has to be imported because it is not locally manufactured. The country is loosing a huge amount of foreign currency in importing this and other spare parts. Apart from the high procurement cost import involves long lead time. In order to avoid factory shut downs a lot of spares are also kept in reserve. This leads to very high inventory costs which results in high factory overhead costs. As an attempt to solve these problems the present study was undertaken. The main objective of the work was to ascertain whether local manufacture of a critical spare parts like tilting pad thrust bearing was at all feasible. Design and manufacture of the above mentioned bearing were performed under the present case study. Tests were performed to identify the material of the bearing lobes as well as the composition of the of the white metal layer. Since no working or detail drawing of the part was available in the factory, the different dimensions of the spare part were determined by precision measurements and by analytical methods. Apart from that the sequence of manufacturing operations were so designed as to permit its manufacturing using local facilities. Fixtures required for maintaining the required precision of manufacturing were designed appropriately. The part was subsequently manufactured using technical facilities of BUET and BITAC. The lobes were precisely machined and then white metallising was performed. The bearing lobes were then ground and polished to accurate dimensions. Finally the jobs were checked for quality and are ready for practical tests.

1.0 Introduction:

The agriculture sector plays the most vital role in the economy of our country. It contributes more than 50% to the total GDP of Bangladesh. The present Government has laid special attention to boost up production in this sector. Huge amount of money has been and being invested in agro-support and agro-based industries of Bangladesh.
Fertilizer is the most important element which enhances the agricultural production. So priority has been given to build up fertilizer industry because its contribution to production is quite high. At present there are eight fertilizer factories in our country.

Though theoretical contribution shown by the fertilizer factories are satisfactorily high, yet in reality the contribution is relatively poor. One of the major causes of for this poor contribution is due the low capacity utilization of the machineries and equipment. By all accounts, it seems that fertilizer factories are suffering from an overload of extra price. It has been found that if the machineries could be maintained using locally manufacture spare parts the cost of production of fertilizers would have been lower.

Five years back a study was undertaken on the experimental manufacture of spare parts for Urea Fertilizer Factory, Ghorashal Ltd. Tilting pad thrust bearing, which is a very expensive spare part, has been selected for test manufacturing. This challenging project has been executed for the last four years by nine final year students of Mechanical Engineering under the supervision of the first author. Different parts of tilting pad thrust bearing have been designed and manufactured by different groups students. The second and the third authors had the opportunity to finalize the project work.

2.0 Raw Material of the part:

The material of the imported parts tilting pad thrust bearing was found to be chromium steel with 12% of chromium. The part was found in the annealed condition. Chromium is in the form of simply carbides(CrC₇, Cr₇C₃) or complex carbides (FeCr₇C₃) these carbides have high hardness and good wear resistance, the corrosion resistance property is due to a thin adherent stable chromium oxide film that effectively protect the steel against many corroding media. This is occurs only when the chromium content exceeds about 10%. Chromium is soluble up to about 13% in iron.

3.0 Design Procedure of Tilting Pad Trust Bearing:

The bearing consists of eight lobes, held around the circumstances of the pad. The detail drawing of the lobe is shown in Fig.1. The following article gives the description of the design procedure of such a bearing lobe. The bottom surface of the part is not parallel with the horizontal plane. One side is slightly protruded with respect to the other side, so if the bottom surface of the part is made parallel with horizontal plane, it would cause some error in calculation, though it would make further calculations easier.

3.1 Determination of the Inclination Angle:

The inclination angle at different sections of the part was found to be different. So several sections on the part were considered. Chord length for each section and vertical heights of both ends of the chord from base were measured (Fig.2).
Fig. 1 Detail drawing of the tilling pad thrust bearing lobe
Table-5: Calculation of back angle of the arc lobe

![Diagram of arc lobe with labeled sections 1 to 6 and annotations h and R]

Fig 2 Determination of the inclination angle

Lengths of different chords are listed in Table-1.

Table-1: Chord length at different sections of the bearing lobe

<table>
<thead>
<tr>
<th>No. of obs.</th>
<th>Chord no.</th>
<th>Chord Length (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1</td>
<td>68.20</td>
</tr>
<tr>
<td>2</td>
<td>2</td>
<td>63.80</td>
</tr>
<tr>
<td>3</td>
<td>3</td>
<td>58.80</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>50.80</td>
</tr>
<tr>
<td>5</td>
<td>5</td>
<td>47.00</td>
</tr>
<tr>
<td>6</td>
<td>6</td>
<td>44.30</td>
</tr>
<tr>
<td>7</td>
<td>7</td>
<td>39.80</td>
</tr>
</tbody>
</table>

Table-2: Radial distance between two adjacent chord marked on the arc lobe

<table>
<thead>
<tr>
<th>No. of observation</th>
<th>Distance on the left side, mm</th>
<th>Distance on the right side, mm</th>
<th>Average distance, mm</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>5.76</td>
<td>5.76</td>
<td>5.76</td>
</tr>
<tr>
<td>2</td>
<td>6.40</td>
<td>6.39</td>
<td>6.305</td>
</tr>
<tr>
<td>3</td>
<td>11.08</td>
<td>12.02</td>
<td>11.55</td>
</tr>
<tr>
<td>4</td>
<td>5.28</td>
<td>5.27</td>
<td>5.275</td>
</tr>
<tr>
<td>5</td>
<td>4.38</td>
<td>4.55</td>
<td>4.465</td>
</tr>
<tr>
<td>6</td>
<td>5.88</td>
<td>6.75</td>
<td>6.315</td>
</tr>
</tbody>
</table>
Table 3: Vertical distances from the base to the end of each chord on the arc lobe

<table>
<thead>
<tr>
<th>Chord No.</th>
<th>Vertical distance from left Chord, mm</th>
<th>Vertical distance from right chord, mm</th>
<th>Difference between the two readings, mm</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>10.29</td>
<td>7.72</td>
<td>2.57</td>
</tr>
<tr>
<td>2</td>
<td>10.79</td>
<td>8.56</td>
<td>2.23</td>
</tr>
<tr>
<td>3</td>
<td>11.29</td>
<td>9.38</td>
<td>1.91</td>
</tr>
<tr>
<td>4</td>
<td>12.08</td>
<td>10.67</td>
<td>1.41</td>
</tr>
<tr>
<td>5</td>
<td>12.39</td>
<td>11.24</td>
<td>1.15</td>
</tr>
<tr>
<td>6</td>
<td>12.61</td>
<td>11.58</td>
<td>1.05</td>
</tr>
<tr>
<td>7</td>
<td>12.85</td>
<td>12.18</td>
<td>0.67</td>
</tr>
</tbody>
</table>

\[ \alpha = \text{Inclination angle} \]
\[ b = \text{Chord length} \]
\[ a = \text{Difference in vertical distance} \]
\[ = h_l - h_r \]

where,

\[ h_l = \text{Vertical height from the base to the left side end of chord} \]
\[ h_r = \text{Vertical height from the base in the right side end of chord} \]

Table 4: Calculated values of inclination angle of the arc lobe

<table>
<thead>
<tr>
<th>Chord No.</th>
<th>Inclination angle, ( \alpha ) in degrees</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>2.1587</td>
</tr>
<tr>
<td>2</td>
<td>1.999</td>
</tr>
<tr>
<td>3</td>
<td>1.8592</td>
</tr>
<tr>
<td>4</td>
<td>1.603</td>
</tr>
<tr>
<td>5</td>
<td>1.401</td>
</tr>
<tr>
<td>6</td>
<td>1.3645</td>
</tr>
<tr>
<td>7</td>
<td>0.9633</td>
</tr>
</tbody>
</table>

Since the surface of the job is a part of a cylindrical shaft so the inclination angle versus radial distance plot (from first chord) should give a straight line relationship. Using least square method, the true straight line relationship is obtained.

The back angle of the bottom surface of the part should be taken into account for design purpose. Values of back angle are taken from inclination angle versus radial distance curve. Using least square method another graph was plotted. Back angle versus distance from which corrected values are noted down in Table 6.
Table-5: Calculation of back angle of the arc lobe

<table>
<thead>
<tr>
<th>Observation No.</th>
<th>Radial distance (mm)</th>
<th>Back angle from inclination angle vs. distance curve (degree)</th>
<th>Value of corrected back angle from back angle vs. distance curve (degree)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0.00</td>
<td>0.80</td>
<td>0.80</td>
</tr>
<tr>
<td>2</td>
<td>6.40</td>
<td>0.64</td>
<td>0.53</td>
</tr>
<tr>
<td>3</td>
<td>17.48</td>
<td>0.38</td>
<td>0.388</td>
</tr>
<tr>
<td>4</td>
<td>22.76</td>
<td>0.26</td>
<td>0.255</td>
</tr>
<tr>
<td>5</td>
<td>27.14</td>
<td>0.15</td>
<td>0.15</td>
</tr>
<tr>
<td>6</td>
<td>33.02</td>
<td>0.00</td>
<td>0.00</td>
</tr>
</tbody>
</table>

3.2 Calculation of Radius of the Top Curved Surface of the Arc Lobe:

The radius of the top curved surface of the part can be calculated as follows:

From triangle AOB (Fig.3)

\[
AO^2 = OB^2 + AB^2
\]
\[
AO^2 = (OC - BC)^2 + AB^2
\]
\[
AO^2 = OC^2 - 2OC BC + BC^2 + AB^2
\]
\[
AO^2 = AO^2 - 2OC BC + AB^2 + BC^2
\]
\[
2AO BC = AB^2 + BC^2
\]
\[
AO = (AB^2 + BC^2)/2BC
\]

Here,
- \(AO\) = Radius of the spherical surface, \(R\)
- \(AB\) = Half of the chord length, \(AD\)
- \(BC\) = Radial distance between the outer circumference and the middle point of the chord.

From Fig.3 it is clear that when the right side of the part is raised by an angle to \(\alpha\), then the actual radial distance between the outer circumference and the middle point of the chord can be obtained with reasonable accuracy. So a correction term is to be added while calculating the radial distance between the outer circumference and the middle point of the chord. Considering that the right side of the part is raised by an amount equal to \(h\). For small angle \(\alpha\), the correction will be \(h\):

\[
\sin \alpha = h/c
\]
\[
h = c \times \sin \alpha
\]

Where,
- \(\alpha\) = Angle of inclination
- \(b\) = Chord length

Fig. 3 Calculation of the radius of the top curve
For design purposes, an average radius should be taken which can be found as follows:

\[ R_n = \frac{\sum R}{6} = 113.92 \text{ mm} \]

By rounding off, the average radius may be accepted as 114 mm.

Table 6: Parameters for calculation of the radius of the top curve surface of the arc lobe

<table>
<thead>
<tr>
<th>No. of Obs</th>
<th>h (mm)</th>
<th>h/2 (mm)</th>
<th>BC radial distance between circumference and middle point of chord (mm)</th>
<th>Radius R (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>2.5697</td>
<td>1.2848</td>
<td>5.2248</td>
<td>111.83</td>
</tr>
<tr>
<td>2</td>
<td>2.292</td>
<td>1.1146</td>
<td>4.5546</td>
<td>114.27</td>
</tr>
<tr>
<td>3</td>
<td>1.7866</td>
<td>0.8933</td>
<td>3.8333</td>
<td>114.83</td>
</tr>
<tr>
<td>4</td>
<td>1.4155</td>
<td>0.7077</td>
<td>2.8577</td>
<td>112.45</td>
</tr>
<tr>
<td>5</td>
<td>1.2308</td>
<td>0.4554</td>
<td>4.4319</td>
<td>113.78</td>
</tr>
<tr>
<td>6</td>
<td>1.0462</td>
<td>0.5231</td>
<td>2.1413</td>
<td>114.40</td>
</tr>
</tbody>
</table>

3.3 Calculation of Radius of Curvature of Outside an Inside Curved Surface

The different parameters of the bearing lobe are shown in Fig. 4. For simplicity, radius \( R_1 \) is calculated with the help of the following equations:

\[
R_1 = \frac{(BC^2 + AB^2)}{2BC} \quad \text{(1)}
\]

\[
R_2 = R_1 - a \quad \text{(2)}
\]

\[
R_3 = R_1 - c \quad \text{(3)}
\]

\[
R_4 = R_1 - e + b \quad \text{(4)}
\]

\[
R_5 = R_1 - e \quad \text{(5)}
\]

Where the dimensions are:

\[
a = 1.70 \text{ mm} \quad b = 2.25 \text{ mm}
\]

\[
c = 2.50 \text{ mm} \quad g = 1.21 \text{ mm}
\]

\[
e = 45.53 \text{ mm}
\]

Using equation (1):

\[
R_1 = \frac{(BC^2 + AB^2)}{2BC} = \frac{(47.84 - 41.35)^2 + (69.59/2)^2}{2(47.84 - 41.35)}
\]

\[
R_1 = 96.52 \text{ mm}
\]
Fig. 4 Dimensions of radius of curvature of lobes

Fig. 5 Holding of tilting pad thrust bearing for final machining
Table 8: Data for the calculation of the radii of curvature of the outer and the inner curved surfaces of the bearing lobe

<table>
<thead>
<tr>
<th>No. of obs</th>
<th>Height of bearing lobe of the left side h² (mm)</th>
<th>Height of bearing lobe at the right side h1 (mm)</th>
<th>Average of the two height (mm)</th>
<th>Height of bearing lobe at the middle</th>
<th>Chord length (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>41.54</td>
<td>41.16</td>
<td>41.35</td>
<td>47.84</td>
<td>69.59</td>
</tr>
</tbody>
</table>

Using equation (2):

\[ R_3 = 96.52 - 1.21 = 95.31 \text{ mm} \]

Using equation (3):

\[ R_1 = 96.52 - 2.5 = 94.02 \text{ mm} \]

Using equation (4):

\[ R_4 = 96.52 - 45.93 + 2.25 = 52.84 \text{ mm} \]

Using equation (5):

\[ R_3 = R_1 - ee = 96.52 - 52.93 = 50.59 \text{ mm} \]

3.4 Fixture Design for Final Machining of Tilting Pad Trust Bearing

The curved surface of the fixture (Fig.5, Fig.6) restricts 5 degrees of freedom, the surface parallel to Z axis restricts three degree of freedom and pin A acts as a locator as well as eliminates movements in direction X and Z through its axis. Only an unrestricted movement of a pin a. Thus 3-2-1 method of locating is applied.

The machining curve base containing three points to eliminates to mention in 5 degree of freedom, consisting on one vertical downwards of Y and both clockwise and counterclockwise motion of X and Z axis, support ‘B’ on both sides restricts three additional degrees of freedom’s namely clockwise and counterclockwise rotation around the Y axis and linear horizontal motion along the X and Z direction and the screw A restrict 1 degree of linear motion along + Y direction.

The manufacturing process included the following operations (in a sequential manner):

1. Parting of the shaft
2. Facing
3. Through drilling
4. Boring
5. Outer turning of the shaft
6. Parting and facing to correct dimensions
7. Drilling of 8 holes on the outer cylindrical surface
8. Cutting of 8 internal threads
9. Parting of the lobes
10. Facing of the sides of the bearing segments
11. Milling of the internal surfaces of the segments
12. Machining of the outer and the inner arc surfaces of the segments
13. Face milling of the side surfaces of the segments
14. White metalling of the segments
15. Final grinding of the white metal layer of the segments
16. Truing of the previously drilled holes on the the segments

4.0 Babbiting

The babbiting of bearing lobes are frequently foundry procedures. Babbit is poured over the horizontal surface of the tilting pad trust bearing. Its nominal composition is 87.5% to 89.5% tin, 7% to 8% antimony and 3.5% to 4.5% copper. Babbit metal of the above mentioned composition is generally used in bearing surface requiring a hard, ductile and shock absorbing matrix. The quality of the babbiting bearing depends mainly upon the temperature at which the metal is poured. A high pouring temperature will increases the amount of shrinkage during solidification and this will create severe shrinkage stress. The shrinkage stress may produce cracks which result in bearing failure during service.

It can be melted in pressed steel cast steel or cast iron pots. Applying heat with an ordinary gas or oil heating torch, heat is slowly applied so that melting does not occur too rapidly when the charge becomes molten, the bath is stirred with a bottom to top motion. Overheating is avoided by using an immersion pyrometer to control both and pouring temperature, the optimum temperature is 800°F, the bath temperature depends on the distance of the material must be carried before pouring, if the pouring operation is to be some distance from the melting area the bath temperature should exceed the pouring temperature by 25°F to 50°F depending on the distance involved.

In addition to proper melting the antifriction alloy prior to babbiting steel shells are coated with tin. The lower melting point tin will aid in producing a strong bond between babbitt and the lobe surface.

4.1 Procedure of Babbiting

First of all cleaning of the lobes surface was done by acid bath. For this purpose Hydrochloric acid was diluted with water. Cleaning process was done to remove rust and dust from the surfaces, otherwise tinning would not be possible. Then lobes were fixed in the babbit fixture. It should be noted that babbit fixture was cleaned properly before fixing the lobes in the fixture. Water was added to plaster of paris powder to form a paste. Gaps between the lobes and babbit fixture were sealed with this paste. Then the babbit fixture with lobes were placed over a gas furnace and was heated up to 200-300°C to remove moisture and preheat the lobes. Plaster of paris was used as molding
sand which restrict the flow of white metal away from the lobe surfaces.

After the cleaning and fluxing tinning operations was performed. Tinning is a process where a thin layer of tin (Sn) is coated over a surface. Before tinning lobes were heated approximately 250°C so that they could reach the melting temperature of tin.

After tinning, the mandrel was prepared for pouring. Babbit was poured as soon as possible after the assembly was ready. Pouring was accomplished while tinning, bearing shell surface was still in liquid state. The melted white metal was then poured in the babbit fixture over the flat surfaces of the lobes. Natural cooling process for solidification of white metal was then accomplished.

5.0 Discussion and Conclusion

Bearing is one of the costliest parts for a fertilizer factories. It is due to the high precision, i.e high dimensional accuracy, complicacy of the manufacturing process, high cost of material, etc. Dimensional accuracy is the most important feature of a tilting pad trust bearing. Slight deviation may lead scraping of the job. But it is a very difficult task to maintain this accuracy. Some deviations have been found after completion of the job from the exact dimension. The error remains within acceptable limits. It is to be noted that for the first time this type of high precision bearing is made in our country. So the project may be considered as a test manufacturing venture from where we could reveal our capability in design and manufacturing. However, after quality checking minor deviation in the dimensions of the different lobes from the designed dimensions were observed. Following are the reasons for the slight deviation in dimensional accuracy:

i) Different parts and fixtures were manufactured by different groups of students.
ii) Inaccuracy in fixture manufacturing
iii) Inaccuracy in machining of the lobes.

References