

MECHATRONICS BOOK SERIES

ROBOTICS AND AUTOMATION

Rini Akmeliawati
Wahju Sediono
Nahrul Khair Alang Md. Rashid



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MECHATRONICS BOOK SERIES: ROBOTICS AND AUTOMATION

Editors

Rini Akmeliawati
Wahju Sediono
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TABLE OF CONTENTS

Preface	i
Acknowledgement	ii
Editor	iii
Table of Content	v
1. Visual Tracking for Human Face A.A. Shafie, Iqbal and M.R. Khan	1
2. Robot Design : A Case Study of Team Learning Experience and Outcome A.A. Shafie	7
3. Development Neck Support for Humanoid Robot Head A. A. Shafie, M.N. Kasyfi and N. I. Taufik Y	14
4. Development of Cooperative Mini Robot Amir A. Shafie , Siti E.M.Z and Shazeela A	21
5. Humanoid Robot Arm Amir A. Shafie and Mohd N. Y.	26
6. Designing Human Robot Interaction for Emotionally Expressive Robotic Hear AMIR-III A. Iqbal, A. A. Shafie, and M. R. Khan	32
7. An Overview of Fuzzy Based Person Following Robot T. Alamgir, I. J. Alfar and M. M. Rashid	38
8. Mechanical Design of a Person Following Robot Tarik Bin Alamgir, Ibrahim Jawad Alfar and Muhammad Mahbubur Rashid	43

9. Development of Fuzzy Based Person Following Robot part 2	49
Tarik Bin Alamgir, Ibrahim Jawad Alfar and Muhammad Mahbubur Rashid	
10. Mobile Robot for Fined Tube Inspection	56
Muhammad Mahbubur Rashid	
11. Robot Aided Upper Limb Rehabilitation System: Mechanical Design	64
Shahrul Na'im Sidek, Hidayatullah Mohamed Nawi	
12. Robot Aided Upper Limb Rehabilitation System: Electronics for Sensors and Actuators	69
Shahrul Na'im Sidek, Khairul Anwar Khalid	
13. Robot Aided Upper Limb Rehabilitation System: Results and Analysis	73
Shahrul Na'im Sidek	
14. Snake Robot Locomation in Narrow Space: A Review	79
Raisuddin Khan, Mitsuru Watanabe and Masum Billah	
15. Multiple Hexapod Robot and Collaborative communication	86
Raisuddin Khan, Masum Billah and Mohiuddin Ahmed	
16. Autonomous Unicycle Robot Using Reaction Wheel Pendulum: Mechanical Design	94
Atika Adrina Teepol, Nur Fadhilah Mohd Fauzey, Shahrul Na'im Sidek, Yasir Mohd Mustafah	
17. Autonomous Unicycle Robot Using Reaction Wheel Pendulum: Controller Design	103
Nur Fadhilah Mohd Fauzey, Atika Adrina Teepol, Shahrul Na'im Sidek, Yasir Mohd Mustafah	

HISTORICAL BACKGROUND AND EDUCATION

19. **Develop an Algorithm for Goal Finding Robot using Reinforcement Learning** 118
M. Kamal, R. Khan, S. Bazuhair and M. Billah
20. **Design and Development of 2 Fingers Robotic Hand Actuated by Active Grasping Data** 126
MdMozasser Rahman¹,MohdZoolfadli B MdSalleh
21. **Design and Development of Interactive Fish Robot** 144
MdMozasser Rahman¹,RizaMuhida and Mohammad Zukhair b MohdNazmi
22. **Design and Development of A Digger Robot** 154
MdMozasser Rahman,MohdRuzaini Bin AbdRalim and Others
23. **Glass Wall Cleaning Robot: A Review** 170
Md Mozasser Rahman, Ahmed Murgab Mohammed Mahil, Norsofiana Bt Umar and Nurul Izzati Bt Samsuddin
24. **Glass Wall Cleaning Robot: -Electrical design and control** 177
Md Mozasser Rahman, Ahmed Murgab Mohammed Mahil, Norsofiana Bt Umar and Nurul Izzati Bt Samsuddin
25. **Glass Wall Cleaning Robot: -Electrical design and control** 187
M. M. Rahman, M. R. b A. Ralim
- ✓ 26. **Development of Robotic Manipulator to assist human using brain Signal** 198
Mahbuba Hossain, Raisuddin Khan, and Masum Billah
- ↳ 27. **Glass Wall Cleaning Robot: Mechanical Design** 204
Mahbuba Hossain Raisuddin Khan, and Masum Billah

28. Intelligent SCADA Based Monitoring Scheme for Low Voltage Distribution System	210
M. J. E. Salami, A. M. Aibinua, Mohd Shafie Bin Sani and Nurfaizal Bin Wah	
29. Intelligent SCADA Based Monitoring Scheme for Low Voltage Distribution System	218
Abdullateef Ayodele Isqeel and Momoh Jimoh Eyiomika Salami.	
30. Autonomous Goal Finding Robot	227
M. Kamal, Md. R. Khan, Faisal and M. Billah	
31. Intelligent SCADA Based Pipe Monitoring System	236
M. J. E. Salami, A. M. Aibinua, Mohd Shafie Bin Sani and Nurfaizal Bin Wah	
32. Path Tracking of Car Like Mobile Robot	250
A. A. Isqeela and M. J. E. Salami	
33. A New Energy Efficient Building System	255
M. J. E. Salami, Md. R. Khan, O. A. Abdulquadric	
34. Automatic Car Parking System	262
M. J. E. Salami, Md. R. Khan and O. A. Abdulquadria	
35. Anthropomorphic biped robot	267
A. A. Shafie, M. F. Baharudin	

CHAPTER 19

Develop an Algorithm for Goal Finding Robot using Reinforcement Learning

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19.1 Introduction

Autonomous robots are robots which can perform desired tasks in unstructured environments without continuous human guidance or intervention. All kinds of robots have some degree of autonomy. Different robots can be autonomous in different ways or from different angle point of view. In other word, Autonomy is the other way of describing the level of intelligence any machine has. A fully autonomous robot should have the ability to perform some basic tasks such as gaining information about the environment, work for an extended period without human intervention, mobility to move either all or part of itself throughout its operating environment, without human assistance, and avoid situations that are harmful to people, property, or itself. Machine learning refers to a system capable of the autonomous acquisition and integration of knowledge [1-3]. This capacity to learn from experience, analytical observation, and other means, results in a system that can continuously self-improve and thereby offer increased efficiency and effectiveness.

Machine learning is a wide subfield of artificial intelligence which concerned with the design and development of algorithms and techniques that allow computers to "*learn*". At a general level, there are two types of learning: inductive, and deductive [4].

The major focus of machine learning research is to extract information from data automatically, by computational and statistical methods [5-7]. Hence, machine learning is closely related not only to data mining and statistics, but also theoretical computer science. Human intuition cannot be entirely eliminated since the designer of the system must specify how the data is to be represented and what mechanisms will be used to search for a characterization of the data. Machine learning can be viewed as an attempt to automate parts of the scientific method [8-9].

Finally learning robots are the robots, that learn from their external surroundings for changing/modifying their operating system or just simply updating them through a memory or other means.

19.2 Reinforcement Learning

Reinforcement learning is the knowledge acquired due to several experiences, called Experience based design in the Behavioral Science, with element of reward or punishment to indicate the desirability of the resulting state. It is a branch of Machine Learning. Through Reinforcement Learning the task of the agent/robot is to learn how to obtain the optimal solution/action for any given learning problem for better end results. RL considered as the