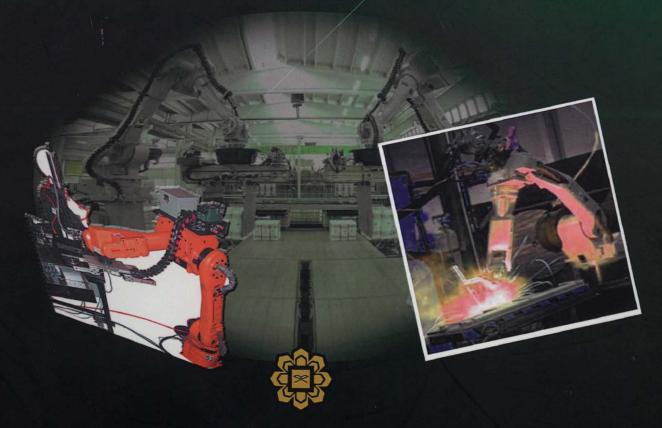
MECHATRONICS BOOK SERIES

ROBOTICS AND AUTOMATION

Rini Akmeliawati Wahju Sediono Nahrul Khair Alang Md. Rashid



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MECHATRONICS BOOK SERIES: ROBOTICS AND AUTOMATION

Editors

Rini Akmeliawati Wahju Sediono Nahrul Khair Alang Md. Rashid



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TABLE OF CONTENTS

| Pro | eface | i |
|------------------|--|--------------|
| Ac | knowledgement | ii |
| Ed | Editor | |
| Table of Content | | \mathbf{v} |
| 1. | Visual Tracking for Human Face A.A. Shafie, Iqbal and M.R. Khan | 1 |
| 2. | Robot Design: A Case Study of Team Learning Experience Outcome A.A. Shafic | and |
| 3. | Development Neck Support for Humanoid Robot Head A. A. Shafie, M.N. Kasyfi and N. I. Taufik Y | 14 |
| 4. | Development of Cooperative Mini Robot Amir A. Shafie, Siti E.M.Z and Shazeela A | 21 |
| 5. | Humanoid Robot Arm Amir A. Shafie and Mohd N. Y. | 26 |
| в. | Designing Human Robot Interaction for Emotionally Expre Robotic Hear AMIR-III A. Iqbal, A. A. Shafie, and M. R. Khan | essive 32 |
| 7. | An Overview of Fuzzy Based Person Following Robot T. Alamgir, I. J. Alfar and M. M. Rashid | 38 |
| 8. | Mechanical Design of a Person Following Robot Tarik Bin Alamgir, Ibrahim Jawad Alfar and Muhammad Mahbubur Rashid | 43 |

| 9, | Development of Fuzzy Based Person Following Robot part 2 Tarik Bin Alamgir, Ibrahim Jawad Alfar and Muhammad Mahbubur Rashid | 49 |
|-----|--|-------------|
| 10. | Mobile Robot for Fined Tube Inspection Muhammad Mahbubur Rashid | 56 |
| 11. | Robot Aided Upper Limb Rehabilitation System: Mechanical Do Shahrul Na'im Sidek, Hidayatullah Mohamed Nawi | esign 64 |
| 12. | Robot Aided Upper Limb Rehabilitation System: Electronics Sensors and Actuators Shahrul Na'im Sidek, Khairul Anwar Khalid | for 69 |
| 13. | Robot Aided Upper Limb Rehabilitation System: Results Analysis Shahrul Na'im Sidek | and 73 |
| 14. | Snake Robot Locomation in Narrow Space: A Review Raisuddin Khan, Mitsuru Watanabe and Masum Billah | 79 |
| 15. | Multiple Hexapod Robot and Collaborative communication Raisuddin Khan, Masum Billah and Mohiuddin Ahmed | 86 |
| 16. | . Autonomous Unicycle Robot Using Reaction Wheel Pendu Mechanical Design Atika Adrina Teepol, Nur Fadhilah Mohd Fauzey, Shahrul Na'im S Yasir Mohd Mustafah | 94 |
| 17. | . Autonomous Unicycle Robot Using Reaction Wheel Pendu Controller Design Nur Fadhilah Mohd Fauzey, Atika Adrina Teepol, Shahrul Na'im S Yasir Mohd Mustafah | 103 |

HISTORICAL BACKGROUND AND EDUCATION

| 19. Develop an Algorithm for Goal Finding Robot using Reinford Learning | ement 118 |
|---|---------------|
| M. Kamal, R. Khan, S. Bazuhair and M. Billah | |
| 20. Design and Development of 2 Fingers Robotic Hand Actual Active Grasping Data | ted by 126 |
| MdMozasser Rahman ¹ ,MohdZoolfadli B MdSalleh | |
| 21. Design and Development of Interactive Fish Robot | 144 |
| MdMozasser Rahman ¹ ,RizaMuhida and Mohammad Zukhair MohdNazmi | b |
| 22. Design and Development of A Digger Robot | 154 |
| MdMozasser Rahman, MohdRuzaini Bin AbdRalim and Othe | rs |
| 23. Glass Wall Cleaning Robot: A Review | 170 |
| Md Mozasser Rahman, Ahmed Murgab Mohammed Mahil, | |
| Norsofiana Bt Umar and Nurul Izzati Bt Samsuddin | |
| 24. Glass Wall Cleaning Robot: -Electrical design and control | 177 |
| Md Mozasser Rahman, Ahmed Murgab Mohammed Mahil, Norsofiana Bt Umar and Nurul Izzati Bt Samsuddin | |
| 25. Glass Wall Cleaning Robot: -Electrical design and control M. M. Rahman, M. R. b A. Ralim | 187 |
| 26. Development of Robotic Manipulator to assist human using Signal Mahbuba Hossain, Raisuddin Khan, and Masum Billah | brain 198 |
| 27. Glass Wall Cleaning Robot: Mechanical Design Mahbuba Hossain Raisuddin Khan, and Masum Billah | 204 |

| 28. | Intelligent SCADA Based Monitoring Scheme for Low Vo Distribution System M. J. E. Salami, A. M. Aibinua, Mohd Shafie Bin Sani and Nurfaizal Bin Wahi | ltage 210 |
|-----|--|----------------|
| | Truffalzar Bin Walli | |
| 29. | Intelligent SCADA Based Monitoring Scheme for Low Vo Distribution System Abdullateef Ayodele Isqeel and Momoh Jimoh Eyiomika Salar | 218 |
| 30. | Autonomous Goal Finding Robot M. Kamal, Md. R. Khan, Faisal and M. Billah | 227 |
| 31. | Intelligent SCADA Based Pipe Monitoring System M. J. E. Salami, A. M. Aibinua, Mohd Shafie Bin Sani Nurfaizal Bin Wahi | 236 and |
| 32. | Path Tracking of Car Like Mobile Robot A. A. Isqeela and M. J. E. Salami | 250 |
| 33. | A New Energy Efficient Building System M. J. E. Salami, Md. R. Khan, O. A. Abdulquadric | 255 |
| 34. | Automatic Car Parking System M. J. E. Salami, Md. R. Khan and O. A. Abdulquadria | 262 |
| 35. | Anthropomorphic biped robot A. A. Shafie, M. F. Baharudin | 267 |

Mechanical Design of a Person Following Robot

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8.1 Introduction

Person-following is a notable talent that obliges to be recognized by a service robot while it requires completing some human-related tasks. The robot has to stay at a certain safe distance as of the person that is being tracked and simultaneously be in motion in a smooth way which does not show frightening to the person. This chapter deals with the general idea of how the person-following robot based on Fuzzy algorithm project has been implemented. There are many ways to build a mobile robot among this most common systems are wheeled, track and leg robot. In this chapter, a wheel robot is build which is a three wheeler robot, whereas it has two wheels in the back side and one ball casters wheel in the front; makes a good third wheel for 3 wheeled robots.

8.2 Model design using CAD

Before any mechanical development is started, the CAD drawing is essential in projecting shape of the robot. This design is capable of projecting different views such as top view, front view, side view and isometric view of a model. The isometric view gives a three dimensional view which help us in realizing the original shape of our robot virtually.

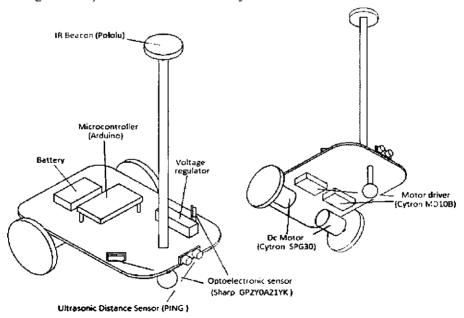


Fig. 1 Isometric view of the robot

8.3 Wheel selection and its arrangements

A three wheeler vehicle or car, further considered as a tri-car, is an vehicle comprise of an exclusive wheel in the dash for direction and two at the forge for power, or two in the dash for maneuvering and one in the forge for power. As a result of its managing supremacy, progressively further