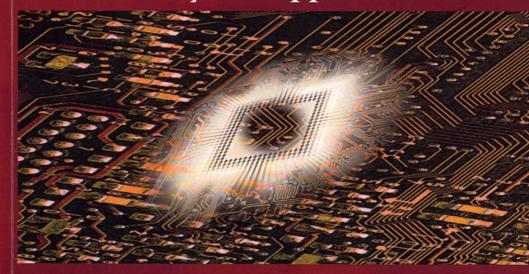
## COMPUTATIONAL INTELLIGENCE IN ROBUST CONTROL

**Theory and Applications** 



Rini Akmeliawati

Research Management Centre
INTERNATIONAL ISLAMIC UNIVERSITY MALAYSIA



# COMPUTATIONAL INTELLIGENCE IN ROBUST CONTROL

Theory and Applications

Editor: Rini Akmeliawati



### Published by: IIUM Press International Islamic University Malaysia

#### First Edition, 2011 ©HUM Press, HUM

All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording, or otherwise, without any prior written permission of the publisher.

Perpustakaan Negara Malaysia

Cataloguing-in-Publication Data

Computational Intelligence in Robust Control: Theory and Applications
Bibliography p.
ISBN

ISBN: 978-967-418-196-3

Member of MajlisPenerbitanIlmiah Malaysia – MAPIM (Malaysian Scholarly Publishing Council)

Printed by:
HUM PRINTING SDN. BHD.

No. 1, Jalan Industri Batu Caves 1/3 Taman Perindustrian Batu Caves Batu Caves Centre Point 68100 Batu Caves Selangor Darul Ebsan.

## TABLE OF CONTENTS

Pro	eface	i
Ac	knowledgement	iii
Ed	litor	iv
Tal	ble of Content	v
1.	Computational Intelligence in Robust Control: A Review R. Akmeliawati and S. M. Raafat	1
2.	Real-Coded Moga For Intelligent Control Of A Manoeuvring System S. F. Toha and M. O. Tokhi	Flexible 28
3.	Optimized LQR Controller Synthesis For 3DOF Helico Multi-Objective Differential Evolution (MODE) I. B. Tijani, R. Akmeliawati, A. Legowo, A. G.A. Muthalif	pter Using 57
4.	PSO-Based Robust Controller Design For A Rotary Pendulum Stabilization M. I. Solihin, R. Akmeliawati, A. Legowo	y Inverted 89
5.	Design And Application Of Intelligent Fuzzy Contro Quarter Car Suspension System Md. Mahbubur Rashid	ller On A 113
6.	Intelligent Robust Control for Precise Tracking Performant X-Y Positioning System S. M. Raafat and R. Akmeliawati	nce of 147

### Chapter 5

## DESIGN AND APPLICATION OF INTELLIGENT FUZZY CONTROLLER ON A QUARTER CAR SUSPENSION SYSTEM

Md. Mahbubur Rashid
Intelligent Mechatronics System Research Unit,
Department of Mechatronics, Faculty of Engineering.
International Islamic University Malaysia

#### Abstract

Conventional car suspension systems are usually passive, i.e have a limitation in suspension control due to their fixed damping force. Active suspension system is expensive, complex and unable to contribute any damping force in case of controller failure. Semi-active suspension system which is a modification of active and passive suspension system has been found to be more reliable and robust but vet easier and cheaper than the active suspension Magneto Rheological (MR) damper, which is the latest type of system. damper, can be used for the simulation and online test. Various Intelligent fuzzy based controllers have been designed in this chapter for both active and semi-active system using MR damper. Different inputs and fuzzy rules have also been used in the different fuzzy logic controllers designed. Adjustable damper is fixed in between sprung mass and unsprung mass to control the suspension system. The responses of various controllers were tested with different types of input disturbance, such as sine wave, squarewave, and random number and saw tooth inputs, to simulate the actual road.