Brought to you by INTERNATIONAL ISLAMIC UNIVERSITY MALAYSIA







Back

CROSS-DOMAIN ANALYSIS OF YOLOV8 AND FASTER R-CNN MODELS FOR ENHANCED PRECISION IN MARITIME OBJECT DETECTION

<u>Journal of Engineering Science and Technology</u> • Article • 2025

Abidin, Zulkifli Z. ^{a, b} ⋈; Norazaruddin, Muhammad A. ^{a, b}; Anuar, Tengku A.T. ^{a, b}

Show all information



Abstract

Recent advancements in machine vision, particularly through Convolutional Neural Networks (CNNs), have significantly enhanced object detection in maritime environments. This study focuses on the performance of different object detection algorithms and its respective variants: YOLOv8 and Faster-RCNN across two specialised maritime datasets: the SeaShip and Sea Maritime Dataset (SMD). Through comprehensive intra-domain and cross-domain evaluations, we analysed the models' precision, recall, and mean Average Precision (mAP) metrics over 50 training epochs. Notably, the YOLOv8x variant demonstrated exceptional adaptability to the SMD dataset, achieving high precision and recall rates with scores of 98.3% and 96.1%respectively. Whilst the YOLOv8m variant was more effective on the SeaShip dataset. The Faster R-CNN X101-FPN model variant shared similar metrics to the intra-domain evaluations for the YOLO comparisons, however showed significant improvement for cross-domain evaluation, noticeable for the SMD model, outperforming its YOLO

^a Department of Mechatronics, Kulliyah of Engineering, International Islamic University Malaysia, Kuala Lumpur, 53100, Malaysia

counterpart with an improvement of 47.9% for the mAP(50) score. Likewise, the SeaShip model had an improvement of 4.48% for the same metric This paper highlights the challenges of applying machine vision in maritime settings due to environmental variability and dataset specificity. The cross-domain analysis revealed significant performance degradation when models were applied outside their training dataset, emphasising the need for robust domain adaptation strategies. Our findings underscore the importance of selecting appropriate object detection algorithms tailored to specific dataset characteristics to optimise object detection performance in diverse maritime environments. © School of Engineering, Taylor's University.

Author keywords

Convolutional neural network; Domain adaptation; Faster-RCNN; Machine vision; Maritime object detection; YOLOv8

Funding details

Funding analysis

Details about financial support for research, including funding sources and grant numbers as provided in academic publications.

Francisco number

Funding sponsor	Funding number	Acronym
IUM Engineering Merit Scholarship		
International Islamic University Malaysia See opportunities by IIUM		IIUM
CXSense System		
Ministry of Higher Education, Malaysia See opportunities by MOHE 7		МОНЕ
KOEIEMS		

Funding text

The author gratefully acknowledges the support from the IUM Engineering Merit Scholarship (KOEIEMS) for Outstanding Students. This scholarship has significantly contributed to the completion of the research presented in this paper. This work was supported in part by the Ministry of Higher Education (MoHE) Malaysia and International Islamic University Malaysia

(IIUM); in part by the Research Management Centre; and in part by the project MyLAB22-002-0002 CXSense System for the SURAYA Unmanned Surface Vessel Fleet.

Corresponding authors

Corresponding Z.Z. Abidin

author

Affiliation Department of Mechatronics, Kulliyah of Engineering, International Islamic University Malaysia, Kuala Lumpur, 53100, Malaysia

Email address zzulkifli@iium.edu.my

© Copyright 2025 Elsevier B.V., All rights reserved.

Abstract

Author keywords

Funding details

Corresponding authors

About Scopus

What is Scopus

Content coverage

Scopus blog

Scopus API

Privacy matters

Language

日本語版を表示する

查看简体中文版本

查看繁體中文版本

Просмотр версии на русском языке